

2 **Effects of wildfires on environmental variability:**
3 **a comparative analysis using different spectral indices,**
4 **patch metrics and thematic resolutions**

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9 **Abstract** Knowledge of environmental variability
10 and how it is affected by disturbance is crucial for
11 understanding patterns of biodiversity and determin-
12 ing adequate conservation strategies. The aim of this
13 study is to assess environmental variability in patches
14 undergoing post-fire vegetation recovery, identifying
15 trends of change and their relevant drivers. We
16 particularly evaluate: the value of three spectral
17 indices derived from Landsat satellite data [Normal-
18 ized Burn Ratio (NBR), Normalized Difference Veg-
19 etation Index (NDVI) and Wetness Component of the
20 Tasseled Cap Transformation (TCW)] for describing
21 secondary succession; the effectiveness of three met-
22 rics (diversity, evenness and richness) as indicators of
23 patch variability; and how thematic resolution can
24 affect the perception of environmental variability
25 patterns. While the system was previously character-
26 ized as highly resilient from estimations of vegetation
27 cover, here we noted that more time is required to fully
28 recover pre-fire environmental variability. Using mean
29 diversity as indicator of patch variability, we found
30 similar patterns of temporal change for the three
31 spectral indices (NBR, NDVI and TCW). Analogous
32 conclusions could be drawn for richness and evenness.

Patch variability, measured as diversity, showed 33
consistent patterns across thematic resolutions, 34
although values increased with the number of spectral 35
classes. However, when the variance of diversity was 36
plotted against thematic resolution, different scale 37
dependencies were detected for those three spectral 38
indices, yielding a dissimilar perception of patch 39
variability. In general terms, NDVI was the best 40
performing spectral index to assess patterns of vege- 41
tation recovery, while TCW was the worst. Finally, 42
burned patches were classified into three classes with 43
similar trends of change in environmental variability, 44
which were strongly related to fire severity, elevation 45
and vegetation type. 46

Keywords Diversity · Richness · Evenness · 47
Landsat · Disturbance · Post-fire recovery 48

Introduction 49 51

Understanding patterns of species diversity and their 52
causes is a traditional theme in ecology (Peet 1974; 53
Huston 1994). Nevertheless, in the current context of 54
loss of biodiversity and decreasing supply of ecosys- 55
tem services (Schröter et al. 2005), it has additionally 56
become an urgent matter of environmental, social and 57
political concern. The occurrence of a species at a site 58
depends on environmental variability, which 59

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60 determines: (1) the range of suitable habitats; (2) their
61 spatial configuration, which influences ecological
62 processes as migration or competition; and (3) their
63 variation over time (Dufour et al. 2006), which is
64 associated with disturbance and succession. Distur-
65 bance has been assumed to be one of the most
66 important factors driving species diversity (“interme-
67 diate disturbance hypothesis” by Connell 1978 and
68 others), even if this relationship has been demonstrated
69 as less consistent than expected (Mackey and Currie
70 2001) and dependent upon the spatial scale of measure
71 (Hammer and Hill 2000; Dumbrell et al. 2008).
72 Consequently, a better knowledge of environmental
73 variability at varying scales, dynamics and drivers of
74 change are crucial for understanding diversity patterns
75 in disturbed landscapes and determining adequate
76 conservation strategies.

77 In the Mediterranean Region, fire is probably the
78 main disturbance (Lavorel 1999), shaping landscapes
79 at different spatio-temporal scales (De Luis et al.
80 2008). In this area fire frequency has increased
81 (Moreno et al. 1998; Pausas and Vallejo 1999) as a
82 consequence of climatic factors (i.e. coincidence of hot
83 and dry seasons and precipitation variability). Another
84 factor is the accumulation of fuel loads subsequent to
85 land abandonment, which results in landscape homog-
86 enization (Suárez-Seoane et al. 2002). Fire has a
87 complex effect on vegetation regeneration, mainly due
88 to differential responses to fire regimes (Wittenberg
89 et al. 2007; Groeneveld et al. 2008). In this sense,
90 Keeley et al. (2005) evaluated four hypothesis (see also
91 Bond and van Wilgen 1996) finding that post-fire
92 recovery patterns are determined by: (1) fire severity
93 and post-fire fluctuations in precipitation (“event-
94 dependent hypothesis”); (2) length of the fire free
95 period, which affects reproductive failure and fuel
96 accumulation (“fire interval hypothesis”); (3) internal
97 density-dependent control, which regulates the change
98 from herbs to woody species (“self-regulatory hypoth-
99 esis”); and (4) extrinsic environmental factors that
100 vary spatially (“environmental-filter hypothesis”). As
101 a result of both disturbance and succession working in
102 changing conditions, landscape becomes a heteroge-
103 neous mosaic of patches with different burning histo-
104 ries, which may enhance its biodiversity (Keeley et al.
105 2005). Since recurrence is high and recovery is quick
106 (due to resprouting abilities or seed bank persistence),
107 Mediterranean mosaics are highly dynamic (Trabaud
108 and Galtié 1996, Díaz-Delgado and Pons 2001).

109 Furthermore, the perception of landscape complexity
110 (i.e. patterns and associated processes) can be prob-
111 lematic because it depends on mapping decisions
112 (Arnot et al. 2004). Landscape pattern measures may
113 vary depending upon choices on spatial, temporal and
114 thematic scales (Levin 1992; Wu et al. 2002; Wu 2004;
115 Saura 2004). However, whilst ecologists are aware of
116 the effect of spatio-temporal scales, few studies have
117 investigated how thematic resolution affects the
118 understanding of the reality. In this sense, Bailey
119 et al. (2007a, b) and Buyantuyev and Wu (2007)
120 demonstrated that different spatial pattern characteris-
121 tics can be identified at different thematic resolutions.
122 Since there is no single optimal thematic resolution in
123 geospatial information, multiscale analyses based on
124 biological traits are required when assessing relation-
125 ships between landscape structure and species behav-
126 iour (Baudry and Burel 1997). For example, coarse
127 thematic resolutions are suitable when analyzing
128 highly mobile or generalist species, which perceive
129 less detail in landscape. By contrast, detailed resolu-
130 tions are more appropriate for species with small
131 movement capacity or with a preference for homog-
132 eneous habitats, which perceive more landscape classes
133 (Suárez-Seoane and Baudry 2002).

134 Classical studies monitor a small number of local
135 fire events for a few years. This make difficult to infer
136 patterns at larger spatial and temporal scales (Röder
137 et al. 2008). At the present, the use of spectral indices
138 derived from multi-temporal satellite data is becom-
139 ing widespread to assess long temporal changes in
140 full sets of landscape elements. In the study area, fire
141 scar mapping (Lozano et al. 2007a), fire risk mod-
142 elling (Lozano et al. 2007b, 2008) and vegetation
143 recovery (Lozano et al. 2005) have been successfully
144 characterized using three spectral indices: Normal-
145 ized Burn Ratio (NBR) (Key and Benson 1999),
146 Normalized Difference Vegetation Index (NDVI)
147 (Rouse et al. 1973) and Wetness Component of the
148 Tasseled Cap Transformation (TCW) (Crist and
149 Cicone 1984). NBR is applied for fire mapping, fire
150 risk modelling and severity estimation. It maximizes
151 reflectance changes related to fire events, since near-
152 infrared reflectance (NIR) decreases due to vegetation
153 removal and mid-infrared reflectance (MIR) increases
154 with the amount of bare soil. NDVI is likely the most
155 widely utilized index in vegetation applications,
156 showing reasonably good results in all phases of the
157 fire cycle. It separates green vegetation from other

158 surfaces because chlorophyll absorbs red light and
 159 reflects NIR wavelengths. TCW is one of the best-
 160 performing spectral indices for monitoring post-fire
 161 recovery. It contrasts visible and NIR wavelengths
 162 (where light absorption by water is low) to SWIR
 163 (short-wave infrared) and MIR bands (where that
 164 absorption is much significant). In most cases,
 165 spectral indices are used as continuous values to
 166 characterize vegetation, or converted into Boolean
 167 variables by means of the application of particular
 168 thresholds to map different landscape elements. Here
 169 we explore the advantages of reclassifying spectral
 170 values into several classes to describe landscape
 171 under different thematic resolutions, avoiding the
 172 uncertainty problems associated with misclassifi-
 173 cation in categorical maps (Shao and Wu 2008).
 174 These data will form the basis for calculating patch
 175 variability by applying different metrics based in
 176 estimations of diversity, since they might give rise to
 177 different conclusions (Yue et al. 2005). Diversity
 178 metrics (Magurran 2004) have been widely used
 179 when characterizing post-fire recovery at a local scale
 180 (e.g. Calvo et al. 2002; Arnan et al. 2006) but they
 181 have been used less often in combination with
 182 spectral indices at a large scale.

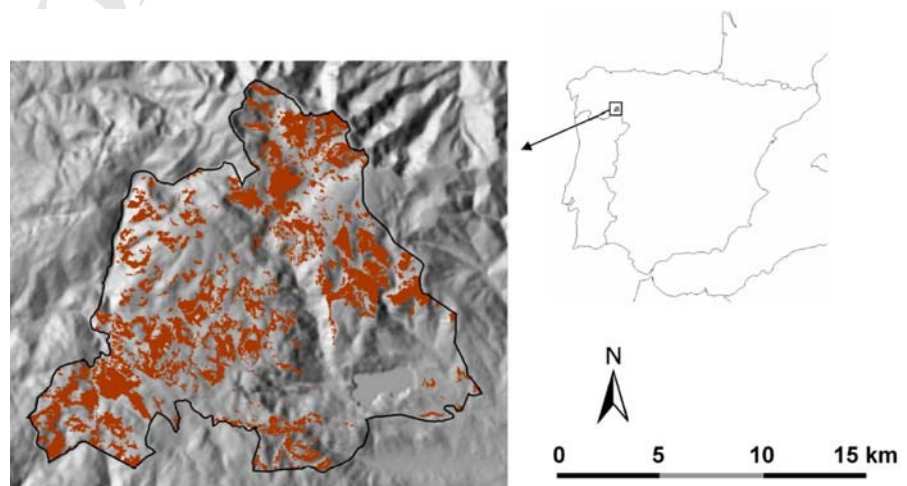
183 The general aim of this study is to detect changes
 184 in environmental variability in patches affected by
 185 post-fire recovery, evaluating the effect of applying
 186 different patch metrics, Landsat spectral indices and
 187 thematic resolutions. More specifically, we try to: (1)
 188 Compare the effectiveness of each spectral index for
 189 assessing vegetation recovery and then environmental
 190 variability (measured as diversity and its components:

191 richness and evenness); (2) Evaluate the role of
 192 thematic scale (i.e. reclassification choices to define
 193 spectral classes) on the results, looking for scale
 194 dependencies; (3) Identify types of temporal change
 195 in patch variability and their environmental drivers.

196 Study area

197 The study area is the Natural Park of Lago de
 198 Sanabria y Alrededores, in north-western Spain
 199 (Fig. 1), which comprises about 23,000 ha. Land-
 200 scape pattern is patchy as a consequence of a long
 201 history of fire events and human activities. At
 202 elevations ranging from 900 to 1,300 m.a.s.l. (where
 203 most of local population lives), woodlots of *Quercus*
 204 *pyrenaica* and riparian communities of *Salix* spp.
 205 occur in a matrix of mixed shrubland (mainly *Erica*
 206 spp. and *Genista* spp.). At higher elevations (1,300–
 207 2,100 m.a.s.l.), where topography is steep, the main
 208 landscape element is a fire-adapted heathland com-
 209 munity dominated by *Erica australis* and, to a lower
 210 extent, *Calluna vulgaris*. Fire events, the main
 211 problem for wildlife conservation, take place very
 212 frequently during early spring (mid-late March) and
 213 summer (July to late September). Fire ignition is
 214 mainly attributed to the local population (about 90%,
 215 Gutierrez, pers. com.), which has been using fire for
 216 centuries to manage vegetation. During the study
 217 period (1991–2005), 24.90% of the area was burned
 218 once, 4.75% twice, 0.40% three times and 0.05% up
 219 to four times. See Lozano et al. (2007b) for a more
 220 detailed description.

Fig. 1 Location of the study area in Spain. The figure shows heathland patches, the landscape elements most affected by fire, superimposed on shaded relief



221 **Materials and methods**

222 A general scheme of the methodology developed in
223 this paper can be found in Fig. 2.

224 Satellite data, maps of burned areas and patch
225 selection

226 One Landsat image was acquired for each year
227 throughout the period 1991–2005 (eleven TM and
228 four ETM + images) covering the Natural Park. Most
229 of the images were taken in late summer (August and
230 September) in order to consider the majority of the
231 burning season. Geometric correction (Palá and Pons
232 1995) was based on ground control points (at least 50)
233 defined on the un-referenced images (50 × 50 km)
234 with the support of orto-photographs at 70 cm (year
235 2000). 60% of the points were used to estimate the
236 geometric fit (second order 3D polynomial) and the
237 remaining 40% for validation purposes. The resamp-
238 ling option was the Nearest Neighbor Algorithm. The
239 sub-pixel georectified images were then radiometri-
240 cally corrected using the algorithms proposed by
241 Markham and Barker (1986) and Moran et al. (1992).
242 Atmospheric correction was based on the default
243 transmittance method proposed by Chávez (1996).
244 Down-welling transmittance values for bands 5 and 7
245 were taken from Gilabert et al. (1994), whose study
246 area had similar atmospheric conditions to our site.
247 Topographic correction was based on a non-

lambertian empirical model, the C-correction method
(Riaño et al. 2003), derived from the approach of
Teillet et al. (1982). Radiometric normalisation of the
time-series using pseudo-invariant scene features
(Hall et al. 1991) enabled a reliable intercalibration
between TM and ETM + images to a common
reference image.

Maps of burned areas for 1992–2005 (Lozano et al.
2007a) were derived from Landsat images by means of
the differenced Normalized Burned Ratio (dNBR).
Overall accuracy was 88.39%, commission error
10.09% and omission error 14.37%. Patches were
defined as spatial aggregations of pixels with the same
fire history (i.e. recurrence and year of fire event).
Spatial continuity within a patch is maintained con-
sidering the eight neighbors of each pixel. A sample of
ten patches was randomly selected for each year. We
only considered patches burned once during the study
period, since the effect of fire recurrence on environ-
mental variability is not the subject of this paper. Due
to low fire occurrence, years 1993, 1996, 2003 and
2004 were excluded, leaving 10 years for further
analysis. The final number of studied patches was 100
(10 patches × 10 years). Mean patch size was
23.89 ha (SD = 50.38), 48.2% of which covered 5–
10 ha, 30.0% 10–20 ha, 11.74% 20–50 ha, 6.09% 50–
100 ha and 3.9% more than 100 ha.

Definition of classes at various thematic
resolutions from different spectral indices

In order to measure patch variability from spectral
indices, continuous values have to be reclassified into
classes, the number of which is dependent on
thematic resolution. Three spectral indices were used:
NBR (Eq. 1), NDVI (Eq. 2) and TCW (Eq. 3).

$$\text{NBR} = (\rho_{\text{NIR}} - \rho_{\text{SWIR}}) / (\rho_{\text{NIR}} + \rho_{\text{SWIR}}) \quad (1)$$

$$\text{NDVI} = (\rho_{\text{NIR}} - \rho_{\text{RED}}) / (\rho_{\text{NIR}} + \rho_{\text{RED}}) \quad (2)$$

$$\text{TCW} = 0.15 \text{TM}_1 + 0.18 \text{TM}_2 + 0.33 \text{TM}_3 + 0.34 \text{TM}_4 - 0.71 \text{TM}_5 - 0.46 \text{TM}_7 \quad (3)$$

ρ_{NIR} , ρ_{RED} and ρ_{SWIR} are the reflectance of near
infrared, red and short-wave infrared bands, respec-
tively. TM_x stands for the channel reflectance of
Thematic Mapper Sensor.

Values of each spectral index were grouped into
five, nine and 13 classes, thus reflecting three
different thematic resolutions. Since each index has

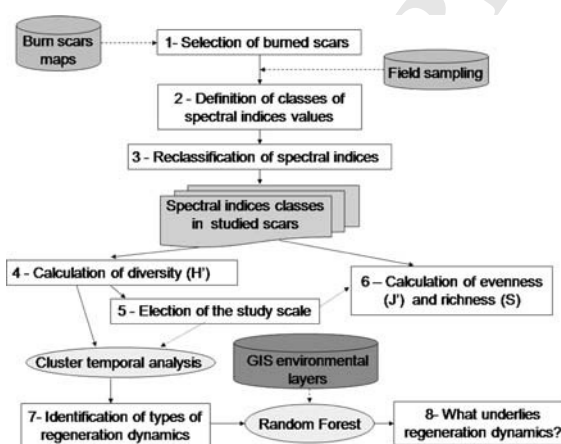


Fig. 2 General schematic representation of the methodology. Steps, databases and statistical analysis are represented in *white rectangular boxes*, *light-gray cylinders* and *dark-gray ovals*, respectively

Table 1 Definition of three thematic resolutions (C5, C9 and C13), containing five, nine and 13 classes of spectral values, respectively

Class	CR5	C9	C13
1	0–30	0–15	0–10
2	30–60	15–30	10–20
3	60–90	30–45	20–30
4	90–120	45–60	30–40
5	>120	60–75	40–50
6		75–90	50–60
7		90–105	60–70
8		105–120	70–80
9		>120	80–90
10			90–100
11			100–110
12			110–120
13			>120

Classes were set up according to ranges of total vegetation cover (values are expressed in percentages). Values were used to calculate patch variability metrics

294 a different range of values which can make the
 295 assemblage and interpretation of the classes confusing,
 296 linear regression analysis was used to transform
 297 spectral data into more understandable and comparable
 298 field vegetation cover values (see Table 1).
 299 Vegetation was recorded in 21 patches in late
 300 summer 2005. We measured total vegetation cover
 301 as the sum of all vertical layers above the soil
 302 (if more than one layer exists, then vegetation cover
 303 can be higher than 100%). The sampling strategy was
 304 based on two factors: time elapsed since the last fire
 305 and size of fire scars. Five experimental units
 306 (30 × 30 m) were randomly distributed within each
 307 patch, so that they corresponded spatially to pixels in
 308 the satellite images. In patches bigger than 50 ha, up
 309 to eight units were defined to account for higher
 310 internal heterogeneity. Within each experimental
 311 unit, we systematically defined five sampling units
 312 of 1 m²: one in the middle and one in each of the
 313 diagonals. Overall, we measured 111 experimental
 314 units and 555 sampling units.

315 Patch variability metrics, general dynamics
 316 and scale dependencies

317 To assess temporal changes in patch variability from
 318 the year before the fire event ($x - 1$) until the seventh

post-fire year ($x + 7$), we utilized spectral data to
 calculate three metrics: diversity, richness and evenness,
 evaluating their role as indicators of environmental
 variability. Diversity (H') was measured by means
 of an adaptation of the Shannon index (Eq. 4; Shannon
 and Weaver 1949) using spectral class frequency as
 input data. Richness (S) was calculated as the number
 of spectral classes in a given patch. Evenness (J')
 was the pixel equi-distribution among spectral classes
 (Eq. 5). The procedure was coded in MatLab (MatLab
 2004).

$$H' = -\sum p_i \log_2 p_i \quad (4)$$

where p_i is the probability of each pixel to allocate
 into each spectral class. $E\{A, B, \dots, i, \dots, T\}$ are
 spectral classes.

$$J' = H' / H'_{\max} \quad (5)$$

where H' is the diversity and H'_{\max} is the logarithmic
 value for richness.

If fire shows a heterogeneous pattern of severity,
 we expect a high number of spectral classes and,
 therefore, a high value of diversity, richness and
 evenness. Parallel reasoning can be applied to
 vegetation recovery. Conversely, low values of
 diversity, richness and evenness will be linked to
 homogeneous patterns originated from very intense/
 weak disturbance/recovery processes.

Diversity values (H') were specifically used to
 explore the existence of scale-dependencies between
 spatial patterns and thematic scale. The observation
 of a phenomenon shows a scale dependency when its
 mean intensity varies with scale. If a statistical
 relationship exists between the scale and the variable
 under analysis, it is possible to undertake scale
 transfers (i.e. to translate the mean value of the
 phenomenon to a certain scale from values obtained
 at another) (Wiens 1989; O'Neill et al. 1991; Auger
 et al. 1992; Suárez-Seoane and Baudry 2002; Peters
 et al. 2007). In order to detect scale dependencies,
 the variance of the annual mean diversity (caused by
 disturbance or recovery, according to the year: $x - 1$,
 x , $x + 1$, ..., $x + 7$) was plotted, for each spectral
 index, against thematic resolution. A break in the
 slope variance/scale will indicate differences in the
 perception of the process across thematic resolutions.
 We then tested whether the slopes of the lines either
 sides of the break were significantly different by

365 running ANOVAs. Measures done at the scale where
 366 such a rupture is detected are especially relevant
 367 because they can be up and down transferred. This
 368 analysis allowed the objective choice of a particular
 369 thematic resolution to simplify the last part of the
 370 study, avoiding redundancy in the results.

371 Identification of classes of environmental
 372 variability dynamics: relevant drivers

373 To identify groups of patches exhibiting similar
 374 temporal trends in environmental variability, we
 375 stored the mean values of Shannon diversity (H')
 376 from the year before the event to the fifth post-fire
 377 year for the three spectral indices (NBR, NDVI and
 378 TCW) and the thematic resolution selected in the
 379 previous step. Here we only used 70 patches,
 380 corresponding to fires occurred between 1992 and
 381 2000 (1993 and 1996 were excluded because of low
 382 fire occurrence, and the years after 2000 because of a
 383 short regeneration period with available data). The
 384 implementation of a hierarchical cluster analysis
 385 allowed groups of patches with similar dynamics to
 386 be defined for each spectral index. These dynamics
 387 were clustered using relative Euclidean distance and
 388 Ward's method, setting the minimum agglomerative
 389 coefficient for group consideration as 80%. Ward's
 390 clustering method minimizes within group variance

relative to between group variance (van Tongeren
 1995). Next, the clusters identified in the previous
 step were re-grouped into the final classes. Analyses
 were undertaken in R statistical package (R 2.4.1.
 2006).

In order to understand the drivers behind the
 identified dynamics, we used the Random Forest
 Algorithm (Breiman 2001) from a set of eleven
 environmental variables likely to be related to
 recovery responses (Table 2). These variables
 describe: (1) frequency of the vegetation types most
 affected by fire events in the surroundings of a given
 pixel, (2) topography and (3) patch features related to
 the fire regime. All these variables were calculated at
 pixel level and then averaged for each patch (except
 patch area). Regarding the estimation of fire severity,
 the standard deviation was also considered because it
 is related to the spatial variability generated by the
 disturbance. The Random Forest procedure is based
 on classification and regression trees. Each node is
 split by the best predictor selected from a subset of
 randomly chosen predictors. This method performs
 very well when compared to other classifiers in
 discriminant analysis, support vector machines or
 neural networks and is robust against overfitting
 (Breiman 2001). In addition, only two parameters
 must be set by the user (number of variables in the
 random subset at each node and number of trees in

Table 2 Environmental variables included in the Random Forest analysis

Variable	Description
<i>Vegetation type</i>	
Young_forest	Frequency (0–1) of young forests in a 7×7 kernel
Shrubland	Frequency (0–1) of mixed shrublands in a 7×7 kernel (dominated by <i>Cytisus scoparius</i> and <i>Genista</i> spp.)
Heathland	Frequency (0–1) of heathlands in a 7×7 kernel (dominated by <i>Erica</i> spp.)
<i>Topography</i>	
Elevation	Elevation (m)
Slope	Slope (degrees)
Solar_rad	Annual solar radiation ($\text{MJ}/(\text{cm}^2 \times \text{year})$)
Time_rad	Solar insolation duration (hours)
Topo_hum	Topographic wetness index (no unit)
<i>Fire-related parameters</i>	
Severity_mean	Mean of fire severity (estimated as the change of the NBR value) for pixels included in the patch
Severity_std	Standard deviation of fire severity (estimated as the change of the NBR value) for pixels included in the patch
Area	Burned patch area (ha)

419 the forest), being the method not very sensitive to
 420 their values (Liaw and Wiener 2002). We established
 421 the number of trees to be created in 50,000 iterations.
 422 The number of variables to be considered in each
 423 split that minimized fit error (assessed by the out-of-
 424 bag observations) was then calculated by means of an
 425 iterative procedure that, in addition, identified and
 426 removed outlier observations. Finally, we ran the
 427 algorithm and explored the error rate of the resulting
 428 model and the importance of each variable measured
 429 as: (1) prediction accuracy of the out-of-bag portion
 430 of the data compared to other variables (mean
 431 decrease in accuracy), and (2) decrease in node
 432 impurities (mean decrease Gini).

433 Results

434 Temporal changes in patch variability: the role
 435 of spectral indices, patch metrics and thematic
 436 scale

437 Mean diversity (H') showed similar patterns of
 438 temporal change across thematic scale, although
 439 values increased when the number of spectral classes
 440 was higher (Fig. 3). It must be highlighted that
 441 diversity drastically increased within the fire year
 442 (associated with the spatial heterogeneity generated

by disturbance), decreasing then abruptly and stabi-
 443 lizing to the seventh post-fire year. The level of
 444 diversity reached at the end of the time span was
 445 always higher than that measured in the pre-fire state.
 446 Comparing diversity values obtained from the three
 447 spectral indices (Fig. 4), we found coherence among
 448 them, with NDVI always showing the highest values
 449 and TCW the lowest. However, some differences
 450 could be observed: NDVI-based values were quite
 451 similar for the year of the event and the first post-fire
 452 year, slowly decreasing in subsequent years, and
 453 almost equalling the values measured the year before
 454 the fire. However, TCW and NBR performed dis-
 455 similarly, as they showed differences among the year
 456 of the event and the following year. Moreover, they
 457 revealed higher values of diversity at the end of the
 458 recovery time series in comparison with the pre-fire
 459 situation. The same results were found for all
 460 thematic resolutions.

Analogous conclusions could be drawn for rich-
 462 ness (S) and evenness (J') (Fig. 5) when compared
 463 with diversity (H') (Fig. 4) to characterize changes in
 464 patch variability from the three spectral indices.
 465 Nevertheless, some slight differences could also be
 466 noticed. For the year of the fire event, no differences
 467 in evenness were detected by spectral indices, with
 468 maximum dissimilarities for richness. Moreover, the
 469 year after the fire, only diversity and evenness
 470

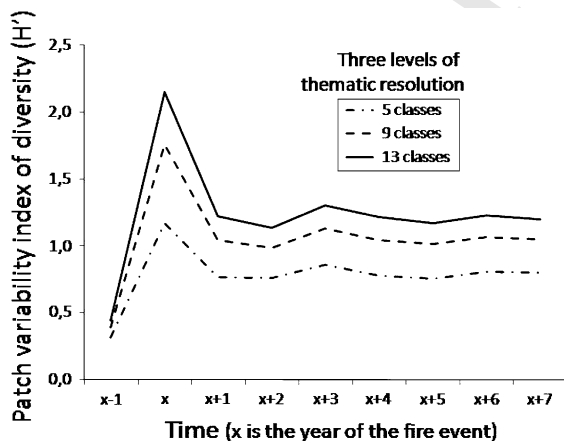


Fig. 3 Temporal changes in patch variability measured as mean diversity (H') from the year before the event ($x - 1$) to the seventh post-fire year ($x + 7$) at different thematic resolutions. The *graph* shows the mean values obtained for the three spectral indices (NDVI, NBR and TCW)

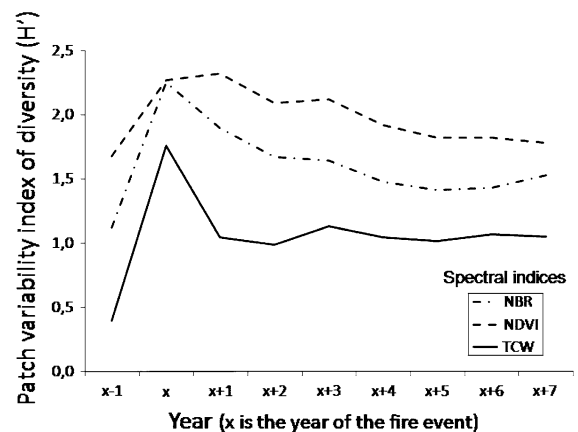


Fig. 4 A comparison of temporal changes in patch variability measured as mean diversity (H') for the three spectral indices. Years are referenced to the year of the event (x). Values correspond to the nine-class thematic scale as an example

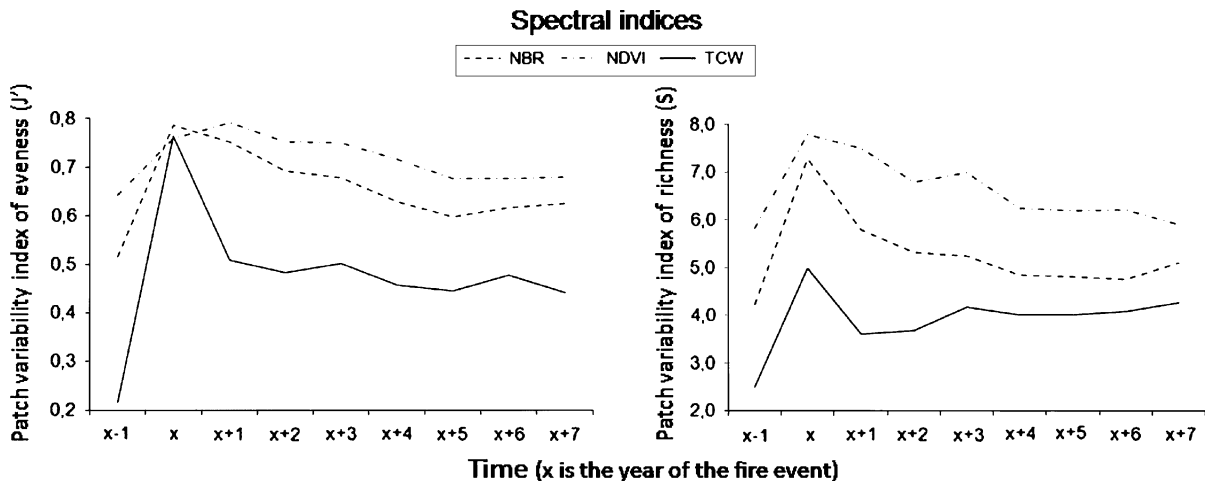


Fig. 5 Temporal changes in patch variability measured as mean evenness (J') and richness (S) for the three spectral indices. Values correspond to the nine-class thematic scale

471 measured from NDVI revealed an increase in
472 variability.

473 Figure 6 plots the variance of the diversity (H')
474 against thematic resolution, showing different
475 responses for the three spectral indices. TCW did not
476 show any visible pattern in this sense ($F = 2.227$,
477 $P = 0.155$, $df = 1$), while a significant slope break
478 was detected at the 9-classes scale for NDVI
479 ($F = 4.679$, $P = 0.046$, $df = 1$). NBR also detected
480 a slight but not significantly break at that resolution
481 ($F = 3.194$, $P = 0.093$, $df = 1$). Therefore, a scale

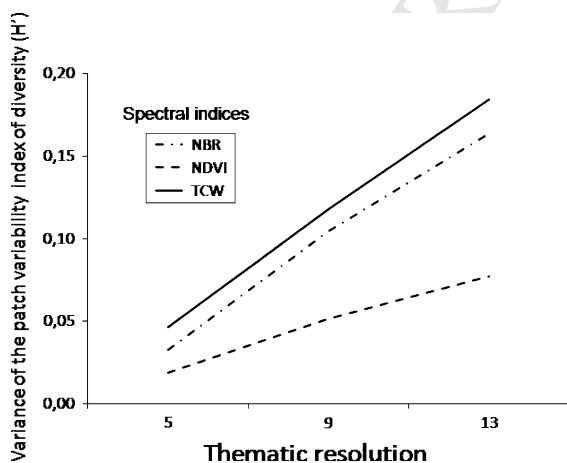


Fig. 6 Variance of the annual mean values of diversity (H'), caused by disturbance or recovery according to the year, plotted against thematic resolution for each spectral index

Table 3 Random Forest models generated for each dynamic identified by the cluster analysis (note that groups based on the TCW index were rejected because of their poor performance)

Index-specific cluster	Final class	<i>n</i>	Total error (%)	Error absence (%)	Error occurrence (%)
G1_NBR	Class 1	54	14.81	9.68	21.74
G2_NDVI	Class 1	52	15.38	3.22	33.33
G2_NBR	Class 2	50	14.00	6.90	23.81
G1_NDVI	Class 2	53	28.30	19.30	40.90
G3_NBR	Class 3	62	35.48	11.63	89.47
G3_NDVI	Class 3	59	30.51	4.76	94.1

The final class assigned to each group, the number of observations (*n*) and the errors are shown for each dynamic

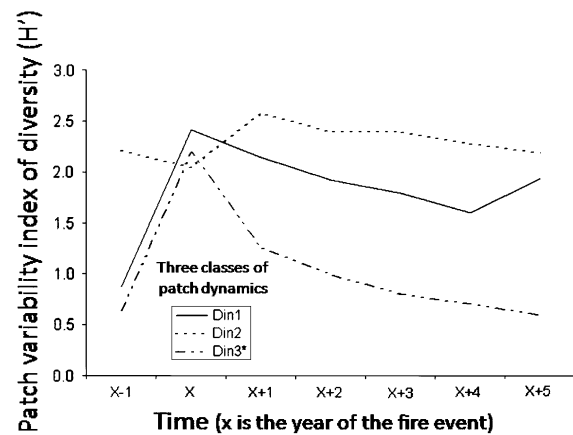


Fig. 7 Dynamic of patch variability for each of the three final classes identified by the cluster analysis

510 Discussion

511 Temporal changes in patch variability: the role
512 of the thematic scale and the spectral indices

513 Many authors have studied ecosystem resilience to
514 fire in Mediterranean systems on the basis of
515 estimations of vegetation cover at either local (from
516 field data; e.g. Calvo et al. 2002) or large scales (from
517 raw spectral values derived from remote-sensing
518 sources; e.g. Díaz-Delgado et al. 2002). The present
519 study offers a complementary approach which
520 allowed the characterization of secondary succession
521 in disturbed patches at different thematic scales, on
522 the basis of environmental variability estimated from
523 satellite data. Variability strongly determines the
524 number and distribution of available habitats and,
525 therefore, is a more relevant determinant of species

occurrence (Dufour et al. 2006) than vegetation cover 526
in itself. We have shown that, while this system was 527
characterised as highly resilient based on estimates of 528
vegetation cover (Lozano et al., pers. com.), longer 529
time scales are required for these communities to 530
fully recover pre-fire levels of environmental variability. 531
This fact highlights the need to combine 532
different approaches to describe ecological complexity 533
in a more realistic way. 534

We found that patches regained most of their pre- 535
fire structural properties during the 2 years following 536
the disturbance. This high resilience to fire has also 537
been found in other Mediterranean areas (Kutieli 538
1994; Díaz-Delgado et al. 2002; Riaño et al. 2002; 539
Wittenberg et al. 2007). In this sense, Pausas and 540
Vallejo (1999) noted that, within the first year after a 541
fire, vegetation cover reached 52.4% in north facing 542
slopes. However, in terms of environmental variability, 543
after the initially rapid regeneration, patches do 544
not reach their original levels and slowly continued 545
recovering, with peaks detectable in the third year, 546
which may correlate with an increase in species 547
richness, as noted by other authors (Ne'eman et al. 548
1995). The level of patch variability achieved at the 549
end of the full time span under study was, in general 550
terms, still higher than that measured in the pre-fire 551
state. This fact suggests that certain structural prop- 552
erties (i.e. diversity) require more time than others 553
(i.e. vegetation cover) to fully recover, probably 554
owing to different rates of ecological processes such 555
as dispersion, colonization or competitive exclusion 556
across the mosaic generated by the disturbance (Hurt 557
and Pacala 1995; Dufour et al. 2006). According to 558
Keely (1991), most species massively disperse their 559
propagules in spring and summer (prior to autumn 560

fires) through passive mechanisms, which may cause a delay in recovery for seeders. Therefore, a primary determinant of similarities between pre- and post-fire states is the dominance of seeders or resprouters in the community, with greater similarities detectable between both states when resprouting species dominate (Keely et al. 2005), as is the case in this study. This is relevant for biodiversity because higher variability implies that more varied environmental conditions and, thus more species, can coexist (Statzner and Moss 2004).

Ecological processes operate at a range of scales in the landscape. Therefore, ecological systems become structured in hierarchies which are specific to each phenomenon, comprising different levels of organization relevant at different scales (Allen and Starr 1982; O'Neill et al. 1986; Urban et al. 1987; Kotliar and Wiens 1990; Wu and David 2002). As a consequence, the scale chosen for examining these processes affects the way in which the system is perceived (He and Gaston 2000). Ecological studies frequently use area-based information derived from field surveys, aerial photography or remote sensing sources. Since the boundaries of these areal units (plots, pixels) are usually arbitrary (or constrained by the resolution of available data), the procedure of defining/changing the scale may show problems related to the Modifiable Areal Unit Problem (Openshaw and Taylor 1981; Jelinski and Wu 1996). In this study, problems may arise from the aggregation of the same set of input data (one for each spectral index) into classes (three thematic resolutions), which often lead to error propagation and controversial results (Wu et al. 2000). This problem should be further explored since it may have significant influences on the determination of relationships among organizational levels and the translation of information across scales. On the other hand, despite its relevance, the analysis of thematic resolution should be done in concert with modifying spatial and, if possible, temporal resolutions. When considering just one scale component, sound conclusions are not warranted. All three scale components are related, making it more relevant to analyze simultaneous scale effects.

In general terms, patch variability (measured as Shannon diversity) due to fire events showed similar patterns of temporal change across thematic resolutions. This is in concordance with Buyantuyev and

Wu (2007), who found that the effects of thematic resolution on many landscape metrics tend to show consistent general patterns. As expected, variability increased with thematic resolution. In this sense, many authors (e.g. Uuemaa et al. 2005) noticed that the effectiveness of metrics to monitor landscape patterns is highly influenced by the way that the map has been defined (i.e. depending on the level of detail of information). Bailey et al. (2007a, b) concluded that data of an intermediate level of thematic resolution are sufficient for general biodiversity monitoring, which is in accordance with our findings. Our patterns of temporal change differed according to the spectral index used to describe the environment, yielding different effects of scale-dependency on landscape perception at different thematic scales. The existence of these scale dependencies can be related to the fact that different species with different life traits perceive environmental variability caused by disturbance/recovery differently (e.g. specialist or poorly mobile species with preferences for homogeneous environments against generalist or highly mobile species living in heterogeneous landscapes; Suárez-Seoane and Baudry 2002).

Trends in environmental variability obtained from the three spectral indices were consistent, allowing for small differences. NDVI appears to perform best and TCW most poorly, a finding contrary to results achieved when evaluating vegetation cover by Lozano et al. (pers. com.). Even if all indices are related to vegetation, each provides different properties. For example, NDVI is more closely linked to photosynthetic activity and NBR to water content and ground signals. Therefore, the former should provide better results when dealing with cover classes (vegetation variability) and the latter when exploring differences between bare soil and vegetation. It seems that photosynthetic activity is homogenised at a lower rate than water content and vegetation cover, which determines the influence of the ground signal.

Diversity, richness and evenness as indicators of environmental variability

Many metrics have been used and “misused” to quantify landscape structure (Li and Wu 2004) during recent decades. Among them, diversity indices have been demonstrated as particularly appropriate for describing landscapes at detailed thematic resolutions

657 while others, such as grain and dominance, work
 658 better at low thematic resolutions (Bailey et al.
 659 2007a, b). Here, we explored three diversity-based
 660 metrics (i.e. Shannon diversity, richness and even-
 661 ness), founding similar trends of change through the
 662 study period. This contrasts with Yue et al. (2005)
 663 who found different tendencies when different diver-
 664 sity metrics were used to measure landscape patterns.
 665 In our case, we can conclude that the three metrics
 666 are redundant if used in combination, as they are
 667 providing similar information. This makes them
 668 useful and coherent indicators (Li and Wu 2004) of
 669 environmental variability only if used independently
 670 of each other, with richness providing the least time-
 671 consuming measure. However, some differences
 672 between the three patch metrics were detected
 673 according to the behaviour of the three spectral
 674 indices when measuring the variability induced
 675 immediately after the disturbance event, with greater
 676 similarity between richness and diversity than even-
 677 ness. Such specific differences between indices can
 678 be due to the water content of the vegetation, which is
 679 related to TCW values, and which seems to be more
 680 spatially homogeneous before and after the fire event
 681 than the features related to NDVI (photosynthesis)
 682 and NBR (ground signal, water content and others)
 683 (Lozano et al. 2007b, 2008).

684 Classes of environmental variability dynamics:
 685 relevant drivers

686 A closer investigation of patch variability dynamics
 687 has shown three main classes of change which were
 688 strongly related, among other factors, to the severity
 689 of fire event, which seriously affects the resprouting
 690 capabilities of shrubland (Keely et al. 2005) and,
 691 therefore, determines post-fire recovery. Class 1 of
 692 patch variability dynamic was associated with the
 693 most heterogeneous pattern of fire severity, which
 694 was responsible for the creation of a mosaic of
 695 patches affected to differing degrees, as reflected in
 696 the highest peak in environmental variability during
 697 the fire event. The other relevant driver explaining
 698 this dynamic was elevation, probably because it is
 699 closely linked with radiation and precipitation, both
 700 largely determining vegetation recovery (Díaz-
 701 Delgado et al. 2002). Radiation is less favourable to
 702 vegetation development because is associated with
 703 large water losses through evapotranspiration (an

effect not compensated for by higher photosynthetic
 activity) (Röder et al. 2008), while precipitation is
 obviously related to higher water availability and,
 therefore, more rapid post-fire recovery. Class 2
 occurred in patches where intense fires homogenized
 the heterogeneous pre-fire spatial pattern, which very
 quickly recovered (after 1 year). This may be
 explained by: (1) the positive relationship between
 fire severity and shrubs found by Keely et al. (2005),
 who theorized that this may be due to the effect of
 high temperatures on the stimulation of dormant seed
 banks, which benefits non-resprouting species; (2)
 scarce vegetation cover before the fire or presence of
 rocky formations in the mosaic, (3) initially hetero-
 geneous water availability (e.g. patches close to a
 water course) or (4) human-related changes. Class 3
 was characterised by very rapid recovery associated
 with low severity fires; in this case, temporary
 habitats created by the fire do not persist for long
 and are rapidly recolonized.

General conclusions

Monitoring spatial and temporal changes in patch
 variability on a regular basis is a valuable tool for
 defining conservation measures for species living in
 fire-affected areas. This paper provides a methodo-
 logical framework useful for environmental managers
 to design policies related to vegetation post-fire
 recovery management on the basis of remote-sensed
 data. The method, which explicitly considers spatial
 heterogeneity, allowed us to (1) identify general
 trends in environmental variability; (2) understand
 the most crucial environmental factors affecting those
 trends; (3) identify levels of organisation within the
 system and scale dependencies where thematic scale
 transfers are possible. The combination of ecological
 (i.e. patch variability metrics) and spectral indices has
 shown promising results that should be further
 explored.

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